Symmetry and Stochasticity: Chandrasekhar and The Phenomenology of Large Scale Structure

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- Motivation: A biased view of dark matters

   Observations and simulations
- Gravitational Instability
  - The spherical (and tri-axial) collapse models
- The excursion set description
  - Percolation/branching process/coagulation descriptions
  - Halo abundances and clustering
  - The forest of merger trees
  - The nonlinear probability distribution function
  - Galaxy clustering



Galaxy Clustering varies with Galaxy Type

How is each galaxy population related to the underlying Mass distribution?

Bias depends upon Galaxy Color and Luminosity

Need large, carefully selected samples to study this (e.g. Norberg et al. 2002 2dFGRS; Zehavi et al. 2005)



# Light is a biased tracer



#### Understanding bias important for understanding mass

You can observe a lot just by watching How to describe different point processes which are all built from the same underlying distribution?

# THE HALO MODEL



# Cold Dark Matter

Simulations include gravity only (no gas)
Late-time field retains memory of initial conditions

• Cosmic capitalism



<u>Co-moving</u> volume  $\sim 100 \text{ Mpc/}h$ 

# It's a capitalist's life ...

- Most of the action is in the big cities
- Newcomers to the city are rapidly stripped of (almost!) all they have
- Encounters generally too high-speed to lead to long-lasting mergers
- Repeated 'harassment' can lead to change
- Real interactions take place in the outskirts
- A network exists to channel resources from the fields to feed the cities

# Cold Dark Matter

- Cold: speeds are non-relativistic
- To illustrate,  $1000 \text{ km/s} \times 10 \text{Gyr} \approx 10 \text{Mpc}$ ; from  $z \sim 1000$  to present, nothing (except photons!) travels more than  $\sim 10 \text{Mpc}$
- Dark: no idea (yet) when/where the stars light-up
- Matter: gravity the dominant interaction

N-body simulations of

gravitational clustering

in an expanding universe



z = 10.155

diemand 2003

## Assume a spherical cow ···



(Gunn & Gott 1972)



# At any given time, nonlinear virialized objects:

Are the same density whatever their mass; They formed from regions of similar initial overdensity, whatever their initial size Exact Parametric Solution ( $R_i/R$ ) vs.  $\theta$  and ( $t/t_i$ ) vs.  $\theta$ very well approximated by...

 $(R_{\text{initial}}/R)^{3}$   $= \text{Mass/}(\rho_{\text{com}}\text{Volume})$   $= 1 + \delta \approx (1 - \delta_{\text{Linear}}/\delta_{\text{sc}})^{-\delta_{\text{sc}}}$ Dependence on cosmology from  $\delta_{\text{sc}}(\Omega, \Lambda)$ , but this is rather weak

# $1 + \delta \approx (1 - \delta_{\text{Linear}} \delta_{\text{sc}})^{-\delta_{\text{sc}}}$

- As  $\delta_{\text{Linear}} \rightarrow \delta_{\text{sc}}$ ,  $\delta \rightarrow \text{infinity}$ - This is virialization limit
- As  $\delta_{\text{Linear}} \rightarrow 0$ ,  $\delta \approx \delta_{\text{Linear}}$
- If  $\delta_{\text{Linear}} = 0$  then  $\delta = 0$ 
  - This does not happen in modified gravity models where  $D(t) \rightarrow D(k,t)!$
  - Related to loss of Birkhoff's theorem when  $r^{-2}$  lost?

# Spherical evolution model

• 'Collapse' depends on initial over-density  $\Delta_i$ ; same for all initial sizes

• Critical density depends on cosmology

Final objects all have same density, whatever their initial sizes
Collapsed objects called halos;
200× denser than background, whatever their mass



(Figure shows particles at  $z\sim2$  which, at  $z\sim0$ , are in a cluster)







#### Assume a spherical herd of spherical cows…

### Initial spatial distribution within patch (at $z\sim1000$ )...





… stochastic (initial conditions Gaussian random field); study 'forest' of merger history 'trees'.

…encodes information about subsequent 'merger history' of object (Mo & White 1996; Sheth 1996) Schematic view of merger history of central object

To this, add dynamical friction, tidal stripping, interactions, etc.



## Motivation for models …

percolation/branching process coagulation/fragmentation excursion set/random walk (Smoluchowski + Chandrasekhar)

••• which all give the same answer

Goal: Use initial conditions (CMB) + model of nonlinear gravitational clustering to make inferences about late-time, nonlinear structures

# THE EXCURSION SET APPROACH

(Epstein 1983; Bond et al. 1991; Lacey & Cole 1993; Sheth 1998; Sheth & van de Weygaert 2004; Shen et al. 2006)

# The Random Walk Model



MASS

# From Walks to Halos: Ansätze

•  $f(\delta_c, s)ds =$  fraction of walks which first cross  $\delta_c(z)$  at s

 $\approx$  fraction of initial volume in patches of comoving volume *V(s)* which were just dense enough to collapse at *z* 

≈ fraction of initial mass in regions which each initially contained  $m = \rho V(1 + \delta_c) \approx \rho V(s)$ and which were just dense enough to collapse at  $z(\rho$  is comoving density of background)  $\approx dm m n(m, \delta_c)/\rho$ 

# Random walk with absorbing barrier

- $f(\text{first cross } \delta_1 \text{ at } s) = {}_0 \int dS f(\text{first cross } \delta_0 \text{ at } S)$   $\times f(\text{first cross } \delta_1 \text{ at } s | \text{first cross } \delta_0 \text{ at } S)$ (where  $\delta_1 > \delta_0$  and s > S)
- But second term is function of  $\delta_1 \delta_0$  and s S
  - because subsequent steps independent of previous ones, so statistics of subsequent steps are simply a shift of origin – a key assumption we will return to later

• 
$$f(\delta_1, s) = {}_0 \int^s dS f(\delta_0, s) f(\delta_1 - \delta_0 s - s)$$

• To solve ...

# First-crossing distributions

- 29 March 1900, Louis Bachelier defends PhD thesis and mathematical finance is born (crossing of constant barrier ~ pricing of options and derivatives)
- Schrödinger studied first crossings of linear barrier



- ... take Laplace Transform of both sides:
- $\mathcal{L}(\delta_1, t) = \int ds f(\delta_1, s) \exp(-ts)$ 
  - $= {}_{O} \int ds \exp(-ts) {}_{O} \int dS f(\delta_{O}, S) f(\delta_{1} \delta_{O}, s S)$  $= {}_{O} \int dS f(\delta_{O}, S) e^{-tS} {}_{s-S} \int ds f(\delta_{1} - \delta_{O}, s - S) e^{-t(s-S)}$  $= \mathcal{L}(\delta_{O}, t) \mathcal{L}(\delta_{1} - \delta_{O}, t)$
- Solution must have form:  $\mathcal{L}(\delta_{l}, t) = \exp(-C\delta_{l})$
- After some algebra:  $\mathcal{L}(\delta_1, t) = \exp(-\delta_1 \sqrt{2t})$
- Inverting this transform yields:
- $f(\delta_1, s) ds = (\delta_1^2 / 2\pi s)^{\frac{1}{2}} \exp(-\delta_1^2 / 2s) ds/s$
- Notice: few walks cross before  $\delta_1^2 = 2s$

# Who needs Laplace transforms?

- $p(\delta_1, s) = \int dS f(\delta_0, S) p(\delta_1, s | \text{first cross } \delta_0 \text{ at } S)$
- (where  $\delta_1 > \delta_0$  and s > S)
- But second term in integral is just  $p(\delta_1 \delta_0 | s S)$ 
  - subsequent steps independent of previous ones, so statistics of subsequent steps are simply a shift of origin
- So

 $\sum_{\delta_0} \int d\delta_1 p(\delta_1, s) = \int dS f(\delta_0, S) \int d\delta_1 p(\delta_1 - \delta_0 | s - S)$  $= \int dS f(\delta_0, S) \times \frac{1}{2}$ 

• And so

 $d \operatorname{erfc}(\sqrt{\delta_1^2/2s})/ds = f(\delta_0, s) \times \frac{1}{2}$ 

# Chandra's factor of 2



# The Mass Function

- $f(\delta_c, s) ds = (\delta_c^2 / 2\pi s)^{\frac{1}{2}} \exp(-\delta_c^2 / 2s) ds/s$ CHANDRASEKHAR 1943
- For power-law  $P(k): \delta_c^2 / S = (M/M_*)^{(n+3)/3}$
- $n(m,\delta_c) dm = (\rho/m)/\sqrt{2\pi} (n+3)/3 dm/m (M/M_*)^{(n+3)/6} \exp[-(M/M_*)^{(n+3)/3}/2]$

(Press & Schechter 1974; Bond et al. 1991)

# The Random Walk Model



MASS

# Excursion Set Approach



# Simplification because…

- Everything local
- Evolution determined by cosmology (competition between gravity and expansion)
- Statistics determined by initial fluctuation field: since Gaussian, statistics specified by initial power-spectrum *P(k)*
- Fact that only very fat cows are spherical is a detail (*crucial* for precision cosmology); in excursion set approach, mass-dependent barrier height increases with distance along walk

The Halo Mass Function

•Small halos collapse/virialize first

Can also model halo spatial distribution
Massive halos more strongly clustered



(current parametrizations by Sheth & Tormen 1999; Jenkins etal. 2001)

# Universal form?

- Spherical evolution (Press & Schechter 1974; Bond et al. 1991)
- Ellipsoidal evolution (Sheth & Tormen 1999; Sheth, Mo & Tormen 2001)
- Simplifies analysis of cluster abundances (e.g. Xray, SZ, Opt)



# X-ray cluster cosmology



#### Vikhlinin et al. 2009

# Random Walks

 Gaussian initial fluctuation field
 + spherical
 evolution model
 = hierarchical
 growth of
 structure

(Bond et al. 1991; Lacey & Cole 1993; Sheth 1998; Sheth & van de Weygaert 2004)



# Voids: Much ado about nothing

- To account for both void-in-void and void-incloud problems, require two barriers:
- Of walks which first cross  $\delta_{\rm v}$  at s, remove those which first crossed  $\delta_{\rm c}$

 $F_{v}(s) = f_{v}(s) - {}_{0}\int^{s} dS F_{c}(S) f_{v}(s|S)$  $F_{c}(s) = f_{c}(s) - {}_{0}\int^{s} dS F_{v}(S) f_{c}(s|S)$ 

• Again, it is the Laplace transforms which behave intuitively, and allow solution

# Inverting Laplace transform:

$$S\mathcal{F}(S, \delta_{\rm v}, \delta_{\rm c}) = \sum_{j=1}^{\infty} \frac{j^2 \pi^2 \mathcal{D}^2}{\delta_{\rm v}^2 / S} \frac{\sin(j\pi \mathcal{D})}{j\pi} \exp\left(-\frac{j^2 \pi^2 \mathcal{D}^2}{2\delta_{\rm v}^2 / S}\right)$$

Who needs Laplace transforms? Chandrasekhar's reflection principle:  $F_v(s) = f_v(s) - f_{c+t}(s) + f_{v+2t}(s) - ...$  = zig - zigzag + zigzagzig - ...(where  $\delta_t = \delta_c + \delta_v$ ) THE NONLINEAR PROBABILITY DISTRIBUTION FUNCTION OF DARK MATTER

(Sheth 1998; Lam & Sheth 2008)

Recall: Spherical evolution very well approximated by 'deterministic' mapping ···

 $(R_{\text{initial}}/R)^3 = Mass/(\rho_{\text{com}} \text{Volume}) =$  $1 + \delta \approx (1 - \delta_0 / \delta_{sc})^{-\delta_{sc}}$ …which can be inverted:  $(\delta_0/\delta_{sc}) \approx 1 - (1 + \delta)^{-1/\delta_{sc}}$ 

# The Nonlinear PDF

Linear theory overdensity

δcrit



• Halo mass function is distribution of counts in cells of size  $v \rightarrow 0$  that are not empty.

- Fraction f of walks which first cross barrier associated with cell size V at mass scale M,
   f(M/V) dM = (M/V) p(M/V) dM
   where p(M|V) dM is probability randomly placed cell V contains mass M.
- Note: all other crossings irrelevant → stochasticity in mapping between initial and final density

- On large scales, barrier falls steeply from large height, so most walks which cross barrier do so only once. So no stochasticity, and  $F(>M|V) = p[>\delta_{in}(M|V)|M]$  where  $(\delta_{in}/\delta_c) = 1 (M/\rho V)^{-1/\delta c}$
- Provides estimate of late-time non-linear PDF if initial linear PDF known; shows why skewness is generic.

 For GRF, linear PDF Gaussian for all scales M; *not* true for most other PDFs, or for non-Gaussian ICs.

 This 'infinite-divisibility' of the Gaussian is also true of the Holtzmark distribution which features in Chandrasekhar's work on Dynamical Friction (sum of several 1/r<sup>2</sup> vectors).

# Correlations with environment



Most massive halos populate densest regions

Key to understand galaxy biasing (Mo & White 1996; Sheth & Tormen 2002)



 $n(m|\delta) = [1 + b(m)\delta]n(m) \neq [1 + \delta]n(m)$ 

### Halo clustering ← Halo abundances



Clustering also strong function of mass: can (should!) use clustering to calibrate mass

The Linear Barrier approximation •  $f(\delta_c, s) ds = (\delta_c^2 / 2\pi s)^{\frac{1}{2}} \exp(-B_c^2 / 2s) ds/s$  $B_c = \delta_c (1 - \beta_V s / \delta_c^2)$ 

•  $d \ln f/d\delta_c = 1 - bias$ =  $1/\delta_c - (B_c/s) (1 + \beta_V s/\delta_c^2)$ =  $1/\delta_c - (\delta_c/s) [1 - \beta_V^2 (s/\delta_c^2)^2]$ 

bias = 1 +  $[(\delta_c^2/s) - 1]/\delta_c - \beta_V^2 (s/\delta_c^2)/\delta_c$ 

Massive halos more strongly clustered

'linear' bias factor on large scales increases monotonically with halo mass

![](_page_51_Figure_2.jpeg)

# $\langle N_{\text{gal}} | m \rangle = f_{\text{cen}}(m) [1 + \langle N_{\text{sat}} | m \rangle]$ $\approx 1 + m/15m_L$

![](_page_52_Figure_1.jpeg)

# Correlations with environment

![](_page_53_Figure_1.jpeg)

![](_page_54_Figure_0.jpeg)

# Environmental effects

- Gastrophysics determined by formation history of parent halo
- All environmental trends come from fact that massive halos populate densest regions
- Greatly simplifies models of galaxy
   formation

- Environment
   = neighbours
   within 8 Mpc
- Clustering stronger in dense regions
- Dependence on density NOT monotonic in less dense regions!
- Same seen in mock catalogs; little room for extra effect!

![](_page_56_Figure_4.jpeg)

Abbas & Sheth 2007

Galaxy distribution remembers that, in Gaussian random fields, high peaks and low troughs cluster similarly

![](_page_57_Figure_1.jpeg)

Broken symmetry between over-and under-dense regions can be understood from the Linear Barrier approximation

 $bias = 1 + [(\delta_c^2/s) - 1] - \beta_V^2 (s/\delta_c^2)]/\delta_c$ 

# The standard model:

- Can rescale halo abundances to 'universal' form, independent of *P(k), z,* cosmology
  - Greatly simplifies likelihood analyses
  - Large voids are similar but less abundant, so require more volume to provide similar constraints
- Intimate connection between abundance and clustering of dark halos
  - Can use cluster clustering as check that cluster massobservable relation correctly calibrated
  - Mass function top-heavy in dense regions
  - All environmental effects come from this correlation
- Unlikely to (do not!) hold at 1% precision

# The future

- Excursion set models of morphology of largescale structure
  - Requires barrier crossing by (at least) 6– dimensional walk
  - Chandrasekhar symmetry arguments work for barrier which is 'sphere'; useful guide to progress
  - Model for dependence of halo bias on quantities other than mass
- Account for correlated steps + correlated walks

# May this subject age as gracefully as did Chandrasekhar

![](_page_61_Picture_1.jpeg)

You may think I have used a hammer to crack eggs, but I have cracked eggs.

# Assumptions of convenience

- Uncorrelated steps
  - Correlated steps (Peacock & Heavens 1990; Maggiore & Riotto 2009)
  - Non-Gaussian mass function ~ given by changing PDF but keeping uncorrelated steps
- Barrier is sharp
  - Fuzzy/porous barriers (Sheth, Mo, Tormen 2001;
     Maggiore & Riotto 2009)
- Ensemble of walks is also random
  The real cloud-in-cloud problem

### Only very fat cows are spherical...

![](_page_63_Picture_1.jpeg)

(Lin, Mestel & Shu 1963; Icke 1973; White & Silk 1978; Bond & Myers 1996; Sheth, Mo & Tormen 2001; Desjacques 2008)

![](_page_64_Picture_0.jpeg)

time

So collapse of 1<sup>st</sup> axis sooner than in spherical model; collapse of all 3 axes takes longer

# Tri-axial (ellipsoidal) collapse

- Evolution determined by properties of initial deformation field, described by 3×3 matrix at each point (Doroshkevich 1970)
- Tri-axial because 3 eigenvalues/invariants; Trace = initial density  $\delta_{in}$  = quantity which determines spherical model; other two (*e,p*) describe anisotropic evolution of patch
- Critical density for collapse no longer constant: On average,  $\delta_{ec}(\delta_{in}, e, p)$  larger for smaller patches  $\rightarrow$  low mass objects

# **Convenient Approximations**

• Zeldovich Approximation (1970):

 $(1 + \delta)_{\text{Zel}} = \prod_{i=1}^{3} (1 - \lambda_i)^{-1}$ 

• Zeldovich Sphere  $(\lambda_1 = \lambda_2 = \lambda_3 = \delta_{\text{Linear}}/3)$ :

 $(1+\delta)_{\text{ZelSph}} = (1-\delta_{\text{Linear}}/3)^{-3}$ 

 $(1 + \delta)_{\text{EllColl}} \approx (1 + \delta)_{\text{SphColl}} (1 + \delta)_{\text{Zel}} / (1 + \delta)_{\text{ZelSph}}$ 

# Triaxial collapse + excursion set description of the morphology of large scale structure

![](_page_67_Figure_1.jpeg)

# Halo abundances/galaxy formation care about morphology

![](_page_68_Figure_1.jpeg)